

## **BALAHARI VIGNESH BALU**

DEEP LEARNING | IMAGE PROCESSING | SENSOR FUSION LOOKING FOR AN EXCITING ROLE TO WORK WITH PERCEPTION +(49) 1766 251 2101 | BALAHARI.BALU@GMAIL.COM

### **SKILLS**

- Programming Languages: C, C++, Python
- Specializations: Object Detection & Tracking | Computer Vision | OpenCV
- Deep Learning:
   PyTorch|Tensorflow
   Pandas|Numpy|Sci-Kit|Seaborn|MatPlotLib
   CNN|CUDA
- Tools: Jupyter Notebook, Google Colab, MS Visual Studio, Visual Code, Anaconda Navigator, Pycharm
- Other Technologies: Git, Docker, Linux, Singularity, ROS(Starter)

#### **CERTIFICATIONS**

- Sensor Fusion Engineer (Udacity)
- Robotics Software Engineer (Udacity – in progress)
- Computer Vision
   Nanodegree(Udacity in progress)

### **EDUCATION**

## MASTER'S IN APPLIED COMPUTER SCIENCE SEPTEMBER 2019 - PRESENT

SRH Hochschule, Heidelberg, Germany (1.6)

# BACHELOR'S IN COMPUTER SCIENCE AND ENGINEERING JULY 2011 - MAY 2015

Anand Institute of Higher Technology, Chennai, India (7.22/10.0)

#### **WORK EXPERIENCE**

## **MASTER THESIS** • FRAUNHOFER INSTITUTE FOR COGNITIVE SCIENCE JUNE 2021 – PRESENT

- Implementation of Evaluation metrics and Key Performance Indicators for Object detection as part of safety framework.
- Proposed and implemented new metrics in 2D Object detection to gain more insights from a Safety Perspective.
- Introductry knowledge on SOTIF and to identify important KPIs to judge performance of DNNs from Safety perspective.

## **RESEARCH INTERN • FRAUNHOFER INSTITUTE FOR COGNITIVE SCIENCE FEBRUARY 2021 – MAY 2021**

- Research for state-of-the-art object detection networks \
  frameworks to train and infer on automotive datasets.
- Research to discover detection of Out-Of-Distribution data without major changes on object detection networks.

## **SOFTWARE DEVELOPER-INTERN • BAYES LABS** *MARCH* 2019 – *JUNE* 2019

- Co-organised boot-camps focused on Machine/Deep Learning as a part of Bayes Labs meetup community.
- Created iPython Notebooks for the participants to work using Google Collaboratory to acquire introductory knowledge across different applications of deep learning.

# **SOFTWARE DEVELOPER-INTERN • DAZTA TECHNOLOGIES AUGUST 2017 – MARCH 2018**

Performed Exploratory Data analysis using Numpy, Pandas, Matplotlib libraries in Python. Developed machine-learning models on the explored data.

- Convolutional Neural Networks in TensorFlow
- Deep Learning (One Fourth Labs)

### LINKS

@ BalahariVignesh



@ Balahari Vignesh



@ balahariVignesh.github.io

### LANGUAGE

- English
- German
- Tamil

#### **HONORS & AWARDS**

STIBET Scholarship for exceptional academic performance

### **HOBBIES**

- Cycling Completed more than 1500kms of cycling around Heidelberg.
- Running Completed 7 marathons in 2019

#### **PROJECTS**

### RESEARCH PROJECT ON EFFECT OF BACKBONE ARCHITECTURES & BASIC CV TECHNIQUES ON CNN

- Designed CNN models to study the effect of convolutions across different layers.
- Implemented edge detectors and compared with results of convolutions and the impacts of using image pyramids.
- Compared basic backbone architectures such as AlexNet, VGG and ResNet.

#### **GERMAN TRAFFIC SIGN RECOGNITION**

- Developed a multi-class image classifier for recognizing German Traffic Signs.
- Implemented a CNN architecture on TensorFlow framework and Fine-tuned hyper-parameters to achieve better validation accuracy.

#### **CAMERA 2D FEATURE TRACKING**

- Implemented different detector and descriptors in OpenCV.
- Implemented state-of-the-art keypoint detectors such as HARRIS, FAST, BRISK, ORB, AKAZE and SIFT, and their performance was compared.
- Performed Descriptor extraction and matching using Brute force and FLANN approach.
- Evaluated different combinations of detectors + descriptors based on their performance and identified the best combinations.

#### **3D OBJECT TRACKING**

- Detected and tracked objects in 3D space from the KITTI Dataset based on camera and lidar measurements.
- Computed time-to-collision based on the data from Camera and LiDAR sensors and compared the results.
- Identified the best Keypoint Detector + Descriptor combinations for object tracking and Time to Collision Computation.

### TO PRESERVE DRIVER'S VIGILANCE BY MONITORING HEAD AND **EYE GAZE DIRECTIONS FOR DROWSINESS DETECTION**

- Developed an active safety monitoring technique for Bachelor thesis using OpenCV to detect drowsiness by continuously monitoring head and eye gaze directions.
- Implemented using Haar Cascades for face detection and tracked eye lid movements to count eye blink rate.
- Deployed a seat belt vibrator to alert driver using Arduino and also alerted with audio signals.